

# Lecture 5 - Tree

AIAA 5037 Advanced Algorithms and Data Structures

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# Outline

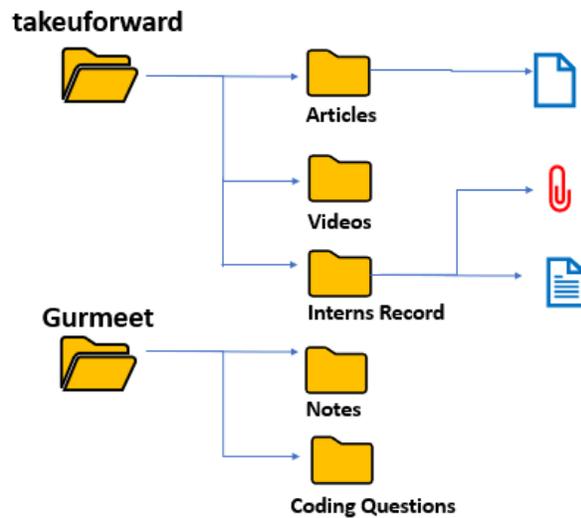
- Trees
- Binary Tree
- Heap
- Heap Sort
- Disjoint Set

# Trees

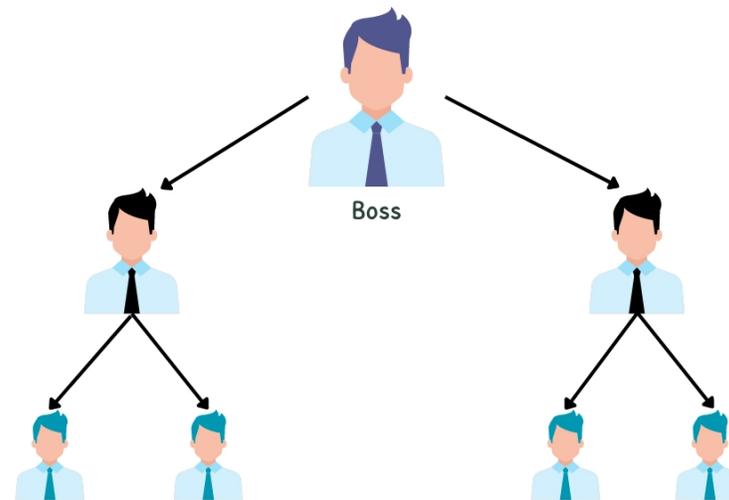
# Tree

A hierarchical structure that consists of nodes connected by edges, a special directed graph

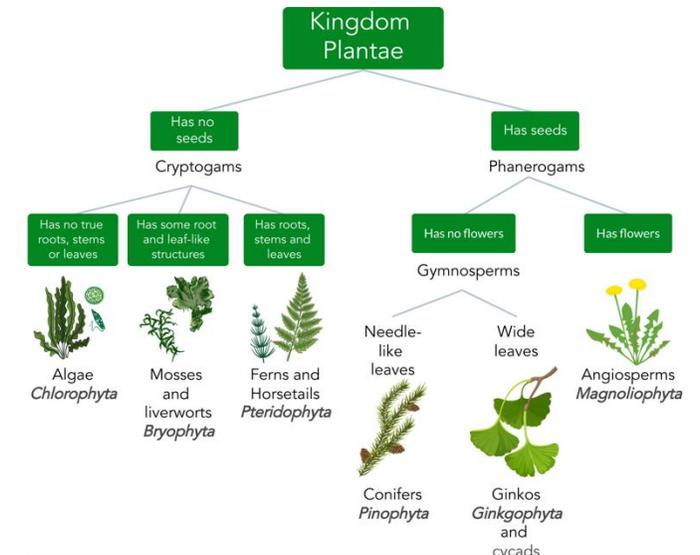
- Each node can be connected to many children, but must be connected to exactly one parent, except for the root node (no parent) – exactly  $n - 1$  edges
- Sometimes we omit the direction



Computer file system



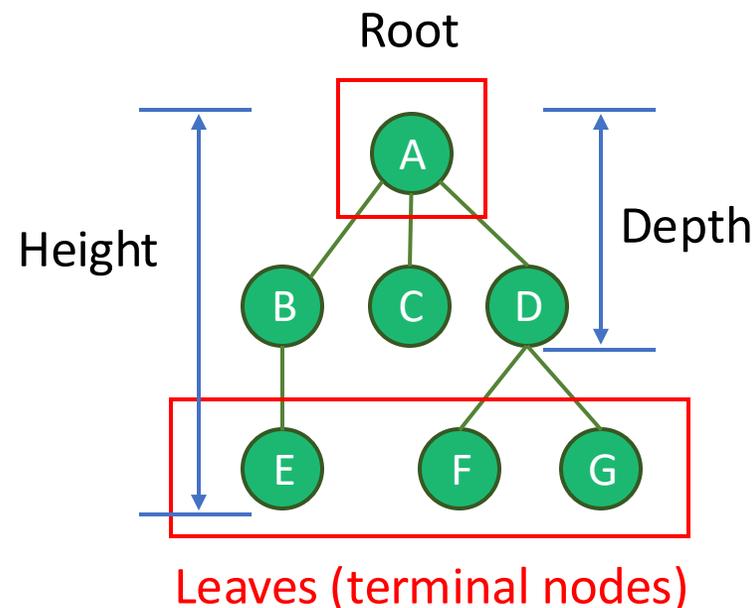
Company organizational structure



Species Taxonomy

# Terminologies

- **Parent:** the node directly above a node
- **Children:** nodes directly below a node
- **Siblings:** nodes that share the same parent
- **Leaves (terminal nodes):** nodes with no children
- **Root:** the node at the top, no parent
- **Height:** maximum distance from root to leaf
- **Depth:** the distance from the root to a node
- **Ancestors:** any node locating on the path to the root
- **Descendant:** all reachable nodes via child edges and any subsequent child edges
- **Subtree:** a smaller tree formed by a node (i.e., the root of the subtree) along with all its descendants

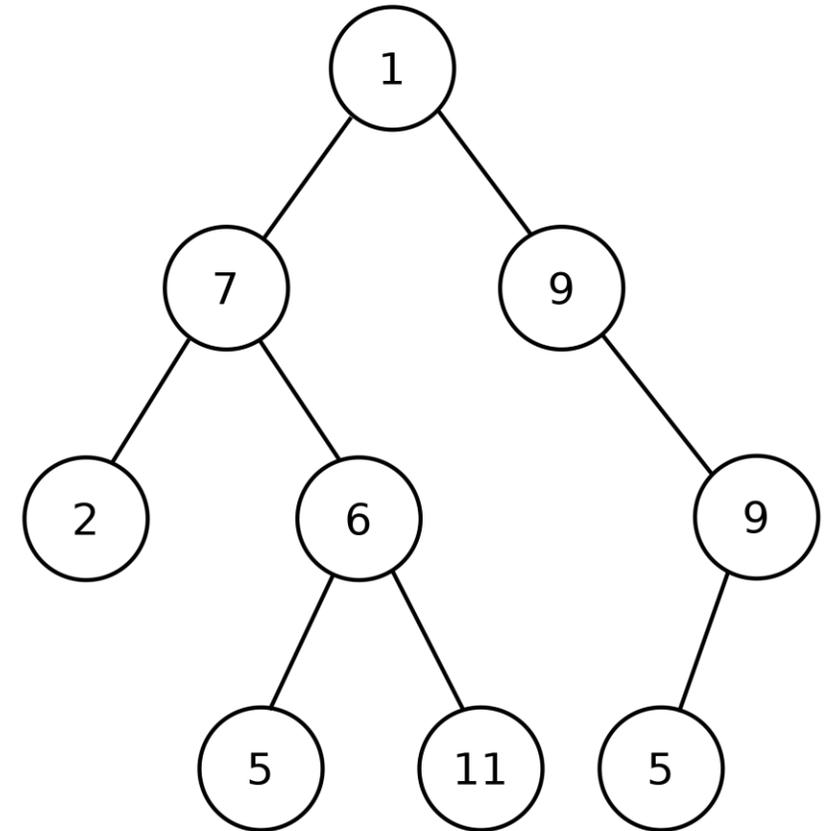


# Binary Tree

# Binary Tree

A tree data structure where each node has at most 2 children (named left and right child)

- Properties (for a binary tree of height  $h$ )
  - The max number of leaves:  $2^h$
  - The min number of leaves: 1
  - The max number of nodes:  $2^{h+1} - 1$
  - The min number of nodes:  $h + 1$

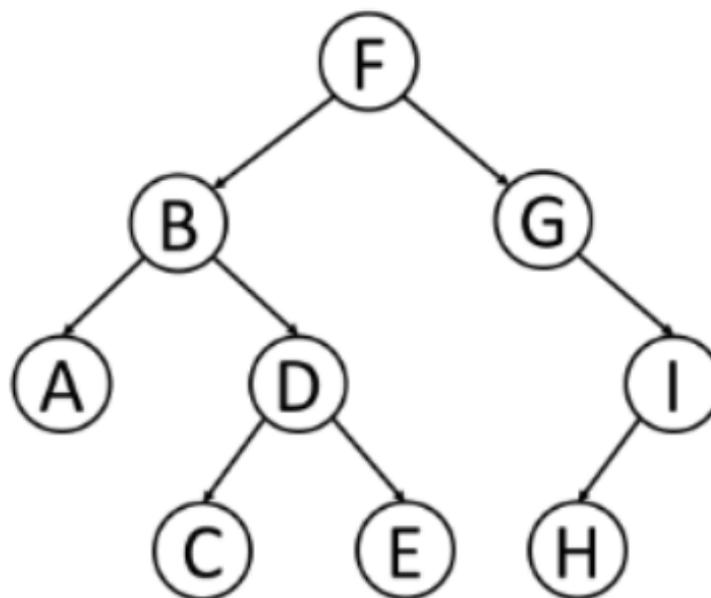


# Binary Tree Traversals

Visit all the nodes of a tree in certain order

- Pre-order: visit **current node** -> traverse **left subtree** -> traverse **right subtree**

```
PREORDER(x)
1. if x != NIL
2.   print x.key
3.   PREORDER(x.left)
4.   PREORDER(x.right)
```



Preorder:

--	--	--	--	--	--	--	--	--	--

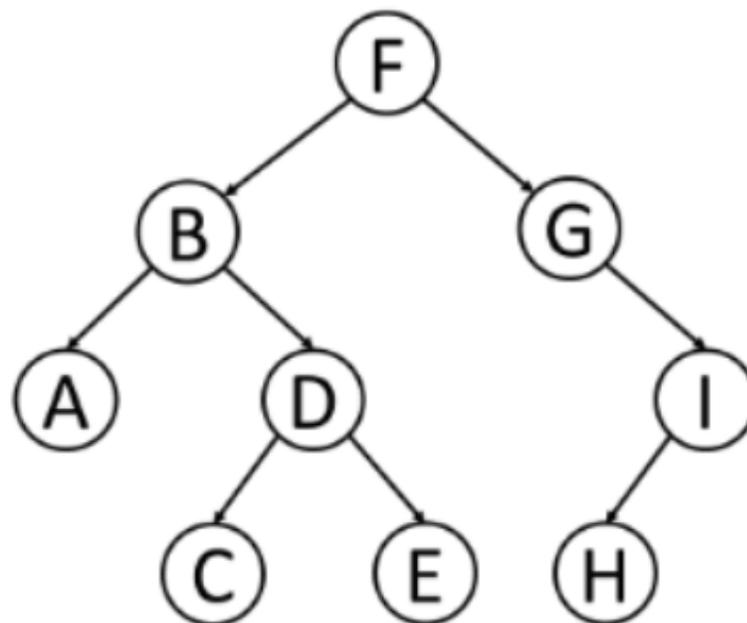
# Binary Tree Traversals

Visit all the nodes of a tree in certain order

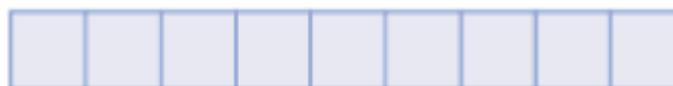
- In-order: traverse **left subtree** -> visit **current node** -> traverse **right subtree**

```
INORDER(x)
```

```
1. if x != NIL
2.   INORDER(x.left)
3.   print x.key
4.   INORDER(x.right)
```



Inorder:



# Binary Tree Traversals

Visit all the nodes of a tree in certain order

- Post-order: traverse **left subtree** -> traverse **right subtree** -> visit **root**

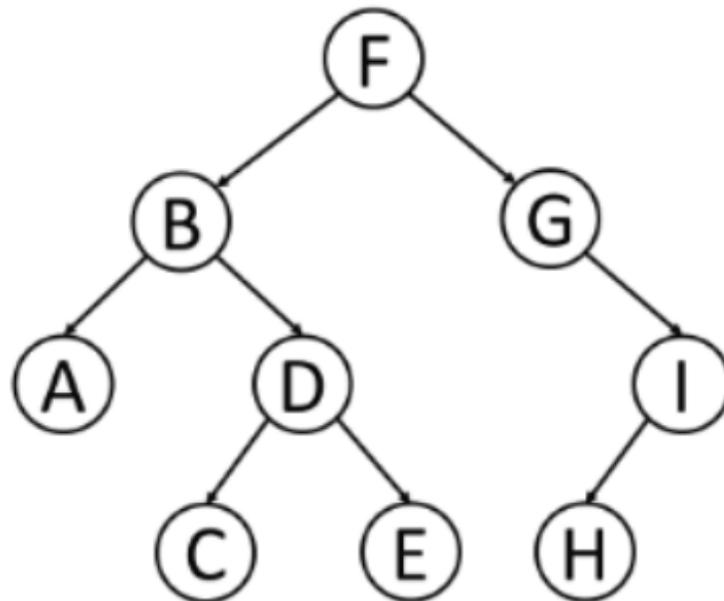
```
POSTORDER(x)
```

```
1. if x != NIL
```

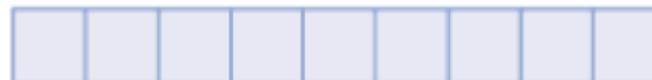
```
2.     POSTORDER(x.left)
```

```
3.     POSTORDER(x.right)
```

```
4.     print x.key
```



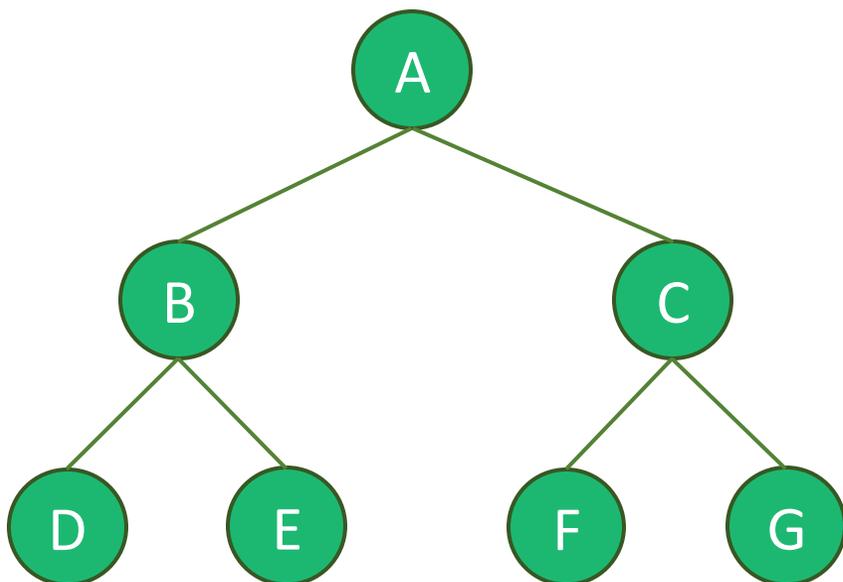
Postorder:



# Binary Tree Traversals

Visit all the nodes of a tree in certain order

- Complexity:  $T(n) = T(m) + T(n - m) + \Theta(1) = \Theta(n)$
- Practice: what is the sequence of output in pre-order, in-order, post-order traversal of the following tree?



```
PREORDER(x)
1. if x != NIL
2.   print x.key
3.   PREORDER(x.left)
4.   PREORDER(x.right)
```

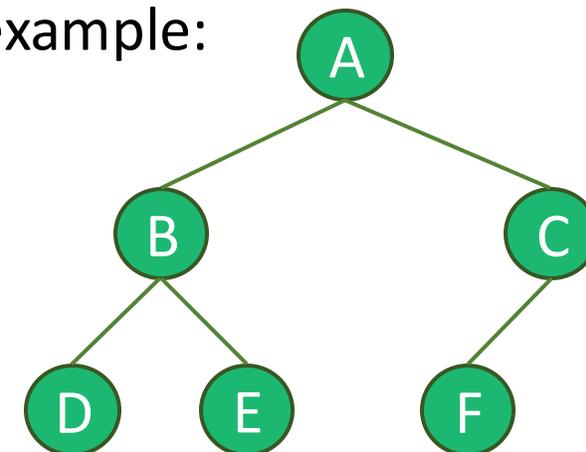
```
INORDER(x)
1. if x != NIL
2.   INORDER(x.left)
3.   print x.key
4.   INORDER(x.right)
```

```
POSTORDER(x)
1. if x != NIL
2.   POSTORDER(x.left)
3.   POSTORDER(x.right)
4.   print x.key
```

## Construct Tree with Traversals

Given inorder and preorder traversal sequence, reconstruct the tree, example:

- Inorder sequence: DBE AFC - [left subtree] [root] [right subtree]
- Preorder sequence: ABDECF - [root] [left subtree] [right subtree]



Observations:

- The first node in preorder sequence is the root - ABDECF
- Root separates inorder sequence into left and right subtrees' inorder sequence - DBE AFC
- The left subtree's inorder sequence is the same length as left subtree's preorder sequence  
– ABDECF

Solution:

- Divide sequences for subtrees
- Construct the two subtrees

```
construct(S_pre, l_pre, r_pre, S_in, l_in, r_in)
1. if l_pre > r_pre: return NIL
2. root = Node(S_pre[l_pre])
3. m = S_in.find(S_pre[l_pre])
4. sz = m - l_in
5. root.left = construct(S_pre, l_pre+1, l_pre+sz, S_in, l_in, m-1)
6. root.right = construct(S_pre, l_pre+sz+1, r_pre, S_in, m+1, r_in)
7. return root
```

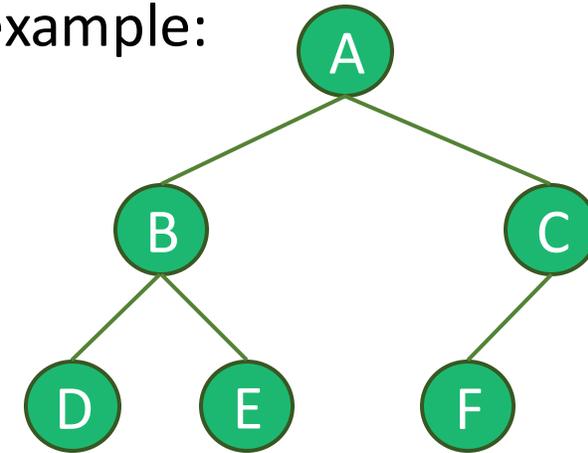
## Construct Tree with Traversals

Given inorder and preorder traversal sequence, reconstruct the tree, example:

- Inorder sequence: DBE AFC - [left subtree] [root] [right subtree]
- Preorder sequence: ABDECF - [root] [left subtree] [right subtree]

How to *find* the root in the inorder sequence?

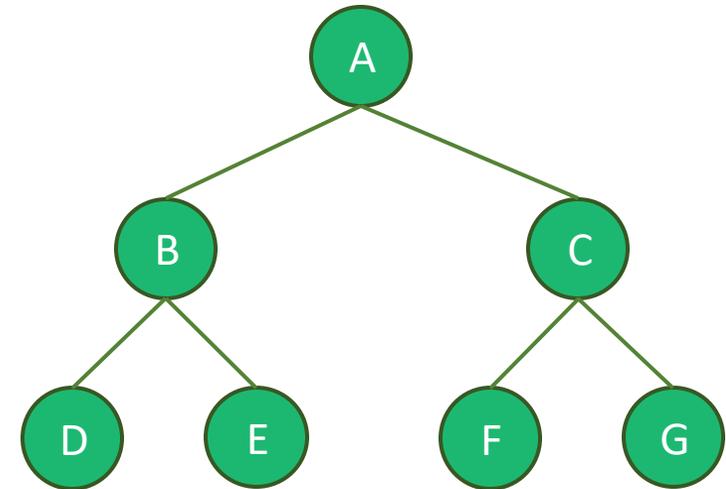
- Naïve: compare 1-by-1,  $\Theta(n)$  find
  - $T(n) = T(m) + T(n - m - 1) + \Theta(n)$
  - $T(n) = \Theta(n \log n)$
- Direct addressing table in advance:  $\Theta(1)$  find
  - $T(n) = T(m) + T(n - m - 1) + \Theta(1)$
  - $T(n) = \Theta(n)$



# Types of Binary Trees

**Perfect binary tree:** all interior nodes have exactly two children, and all leaves are at the same level

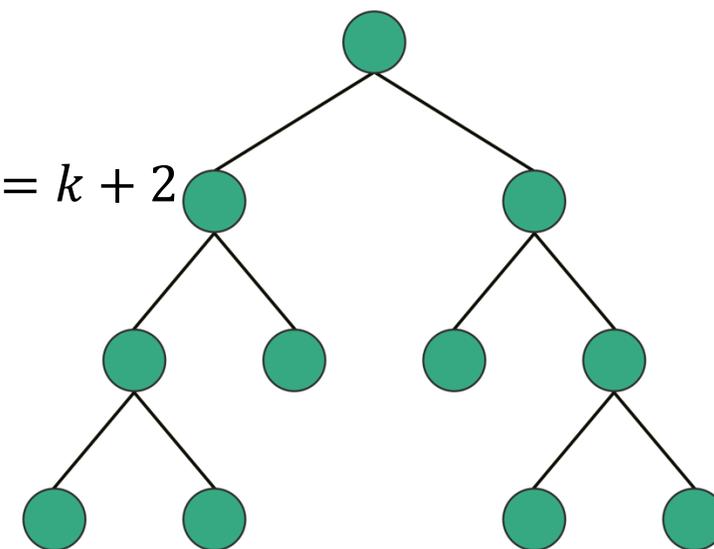
- Property:
  - Level  $i$  has  $2^i$  nodes (prove with mathematical induction)
  - A perfect binary tree of height  $h$  has  $2^{h+1} - 1$  nodes ( $2^0 + 2^1 + 2^2 + \dots + 2^h$ )
  - Half of the total nodes ( $2^h - 1$ ) are interior nodes ( $2^0 + 2^1 + 2^2 + \dots + 2^{h-1}$ )
  - $2^h$  leaves



# Types of Binary Trees

**Full binary tree:** all the interior nodes have 2 children

- A perfect binary tree is always a full binary tree
- Property: let  $i$  be the number of interior nodes, the number of leaves is  $i + 1$
- Proof (mathematical induction)
  - Base case: when  $\#interior = 1$ ,  $\#leaves = 2$
  - Inductive step: supposing when  $\#interior = k$ ,  $\#leaves = k + 1$ 
    - Only adding two child nodes to a leaf make  $\#interior = k + 1$
    - i.e., change 1 leaf to interior node and add two leaves,  $\#leaves = k + 2$
  - Therefore, when  $\#interior = i$ ,  $\#leaves = i + 1$  for any  $i \geq 0$



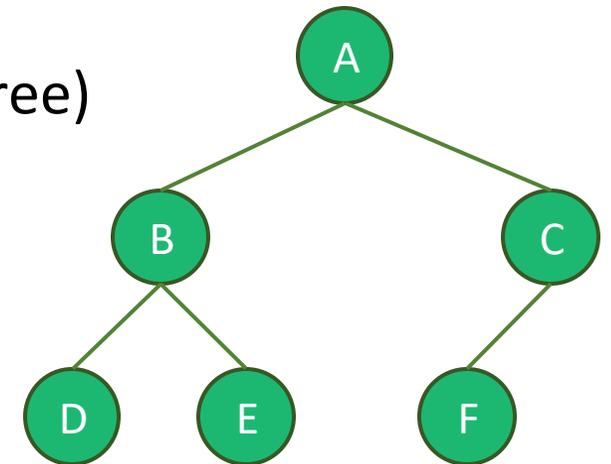
# Types of Binary Trees

**Complete binary tree:** all the levels are filled completely except the lowest level nodes which are filled from as left as possible

A perfect binary tree is always a complete binary tree

Properties:

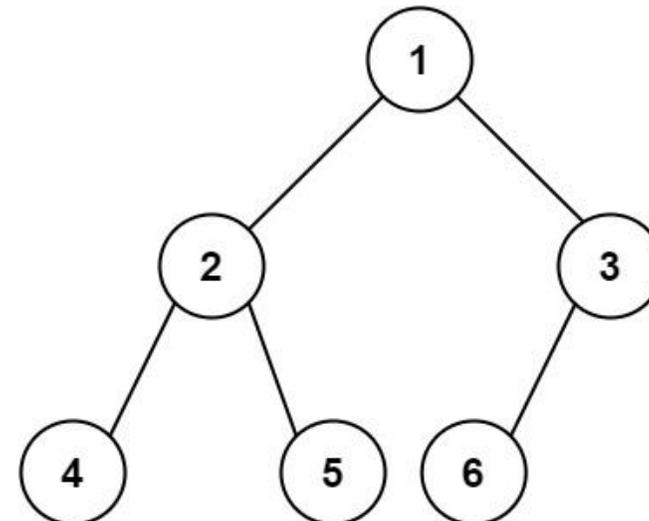
- Level  $i \leq h - 1$  has  $2^i$  nodes
- Has  $2^h$  to  $2^{h+1} - 1$  nodes in total
- $2^{h-1}$  (one node in the last layer) to  $2^h$  leaves (perfect binary tree)



# Count Complete Binary Tree Nodes

Problem: Given the root of a complete binary tree, output the number of the node.

- Naïve solution: binary tree traversal
  - $\#nodes = \#nodes\_in\_left\_subtree + \#nodes\_in\_right\_subtree + 1$
  - $f(root) = f(left\_subtree) + f(right\_subtree) + 1$
  - $\Theta(n)$ , traverse each node once
- Better solution? ---- Hint: **complete binary tree**



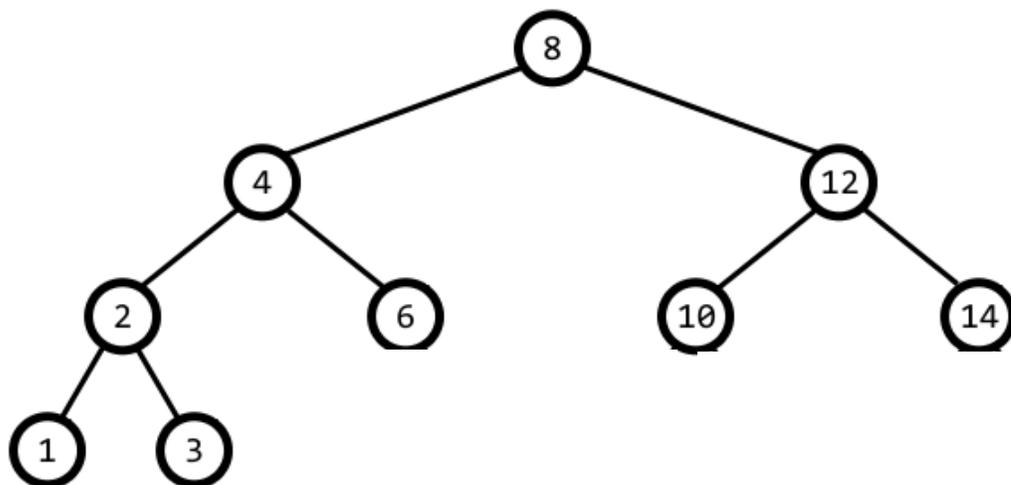
## Count Complete Binary Tree Nodes

Given the root of a complete binary tree, output the number of the node.

- $f(\text{root}) = f(\text{left\_subtree}) + f(\text{right\_subtree}) + 1$

Observation: both left and right subtree are complete binary tree and at least one of them is a perfect binary tree

- Perfect binary tree of depth  $h$  has  $2^{h+1} - 1$  nodes



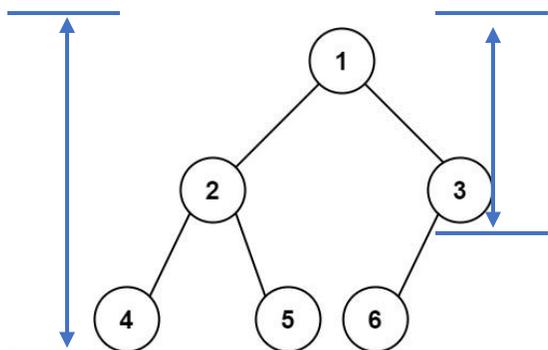
- Both perfect
- Left is perfect
- Right is perfect

**Solution: check whether the current tree is perfect before recursion!**

# Count Complete Binary Tree Nodes

Problem: Given the root of a complete binary tree, output the number of the node

- **Solution:** check whether the current tree is perfect before recursion!
- **Check perfection:** equal distance of leftmost path and rightmost path
  - $d_l(T) = d_l(T.left) + 1$  ---- tell the height of tree
  - $d_r(T) = d_r(T.right) + 1$  ---- tell whether the node is absent
  - Time complexity:  $\Theta(h)$



```
function findLeftHeight(node):  
    height = 0  
    while node is not null:  
        height += 1  
        node = node.left  
    return height
```

```
function findRightHeight(node):  
    height = 0  
    while node is not null:  
        height += 1  
        node = node.right  
    return height
```

# Count Complete Binary Tree Nodes

Problem: Given the root of a complete binary tree, output the number of the node

- **Solution: check whether the current tree is perfect before recursion!**
- **Check perfection:** equal distance of leftmost path and rightmost path

```
function countNodes(root):  
    if root is null:  
        return 0  
  
    leftHeight = findLeftHeight(root)  
    rightHeight = findRightHeight(root)  
  
    if leftHeight == rightHeight:  
        return (2^(leftHeight+1)) - 1  
    else:  
        return 1 + countNodes(root.left)  
                + countNodes(root.right)
```

```
function findLeftHeight(node):  
    height = 0  
    while node is not null:  
        height += 1  
        node = node.left  
    return height  
  
function findRightHeight(node):  
    height = 0  
    while node is not null:  
        height += 1  
        node = node.right  
    return height
```

# Count Complete Binary Tree Nodes

Problem: Given the root of a complete binary tree, output the number of the node

- **Solution: check whether the current tree is perfect before recursion!**
- **Check perfection:** equal distance of leftmost path and rightmost path
- Evaluate time complexity  $T(h)$ :
  - The two sub-trees must have one perfect binary tree (1 recursive subtree, 1 non-recursive subtree with  $\Theta(h)$ ,  $\Theta(h)$  for judging its own perfectness):

$$T(h) = T(h - 1) + \Theta(h) = \Theta(h^2)$$

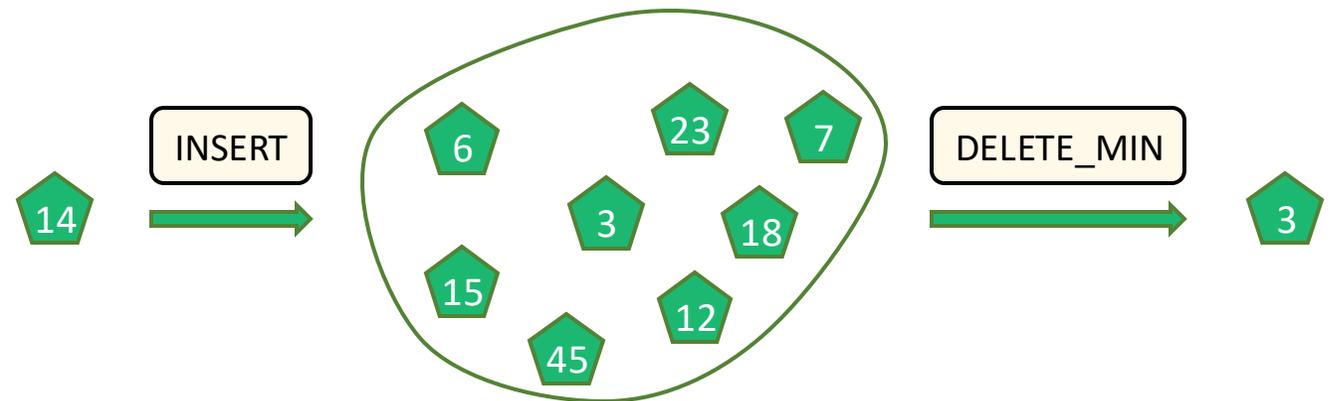
- $h = \Theta(\log n)$  in a complete binary tree

$$T(n) = \Theta(\log^2 n)$$

# Heap

# ADT: Priority Queue

- A dynamic collection where elements have associated *priority*
  - Elements with higher priority are served first (not FIFO and LIFO)
- **Operations:**
  - Pop the smallest element (i.e., largest priority)
  - Insert an element



# Heap

- A tree-based data structure that satisfies the *heap property*:
  - Each node has higher or equal priority than its children
  - $\Rightarrow$  Recursively, grand children
  - $\Rightarrow$  The root always has the highest priority
- E.g., min heap: each node has smaller key than the children's
- Common implementation: **complete** binary tree-based
  - Advantage 1: low height –  $O(\log n)$
  - Advantage 2: can be simulated with array

# Pop Minimum

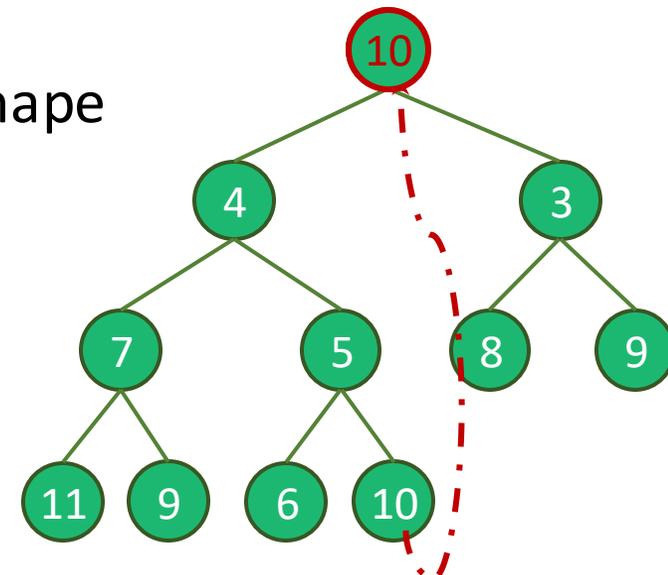
Return the root node and remove it from the heap

**Problem:** replace the root with another node

- Requirement: (1) heap property (2) complete binary tree property
- Recursively move the child node to the root position?
  - Not complete binary tree
- Hint: a complete binary tree with fix number of nodes has fixed shape

**Solution:** move the last element to the root position

- **How to Restore Heap Property?**

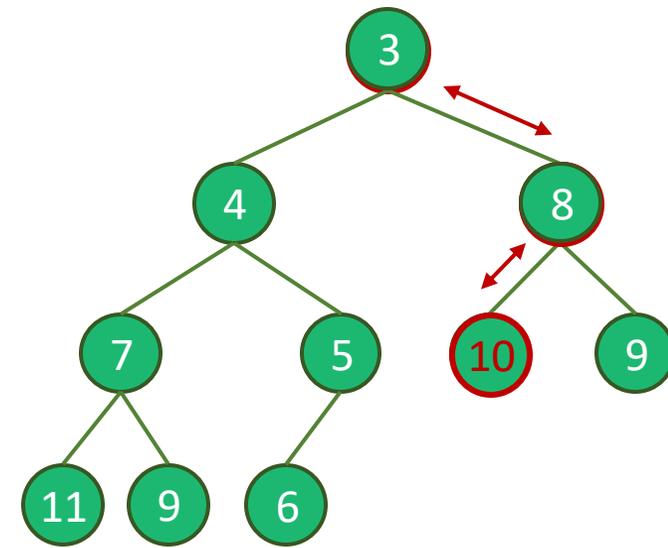


# Pop Minimum

Restore Heap Property: Percolate Down

Core idea: switch the nodes

- Compare the modified node's priority with its children
  - Higher: current subtree is a heap, stop
  - Lower: swap with the child with highest priority
- Repeat until current subtree is a heap or reach a leaf node
- Complexity:  $\Theta(h) \Rightarrow \Theta(\log n)$  for being complete binary tree

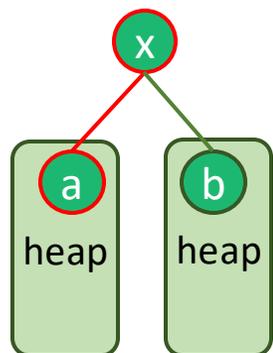


# Pop Minimum

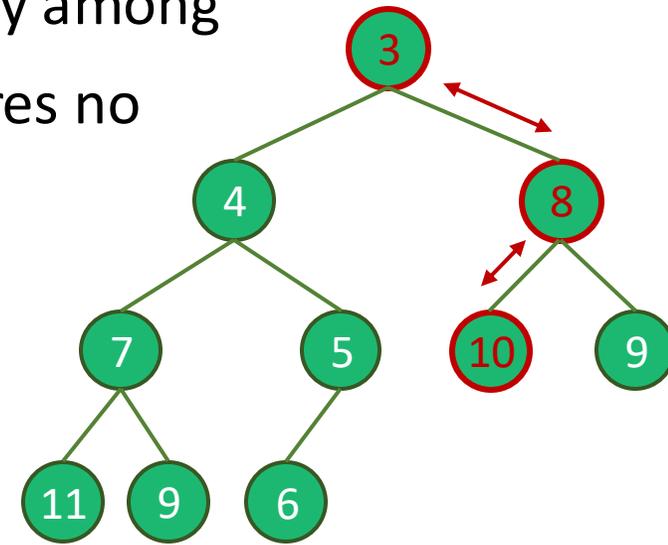
Restore Heap Property: Percolate Down

- Compare the modified node's priority with its children
- Swap with the child with highest priority
- Repeat until current subtree is a heap or reached a leaf node

**Heap Property:** During each swap, the node with the highest priority among the descendants is moved up (like merge sort's merging). This ensures no child has a higher priority than the current node after the swap

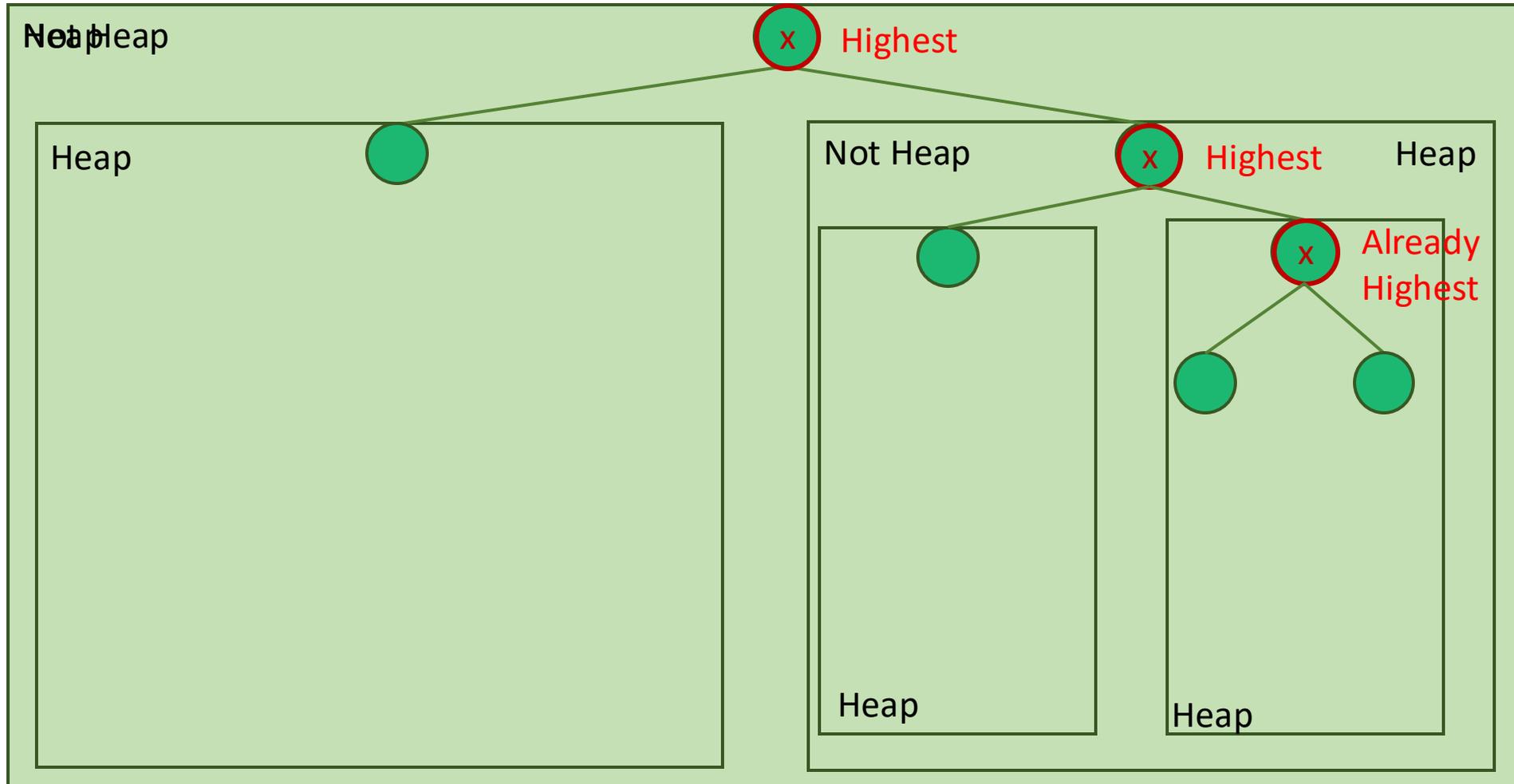


- The highest priority must be between a and b (top of their sub\_heap)



# Pop Minimum

Swapping procedure - supposing always swap with the right child



# Insert Element

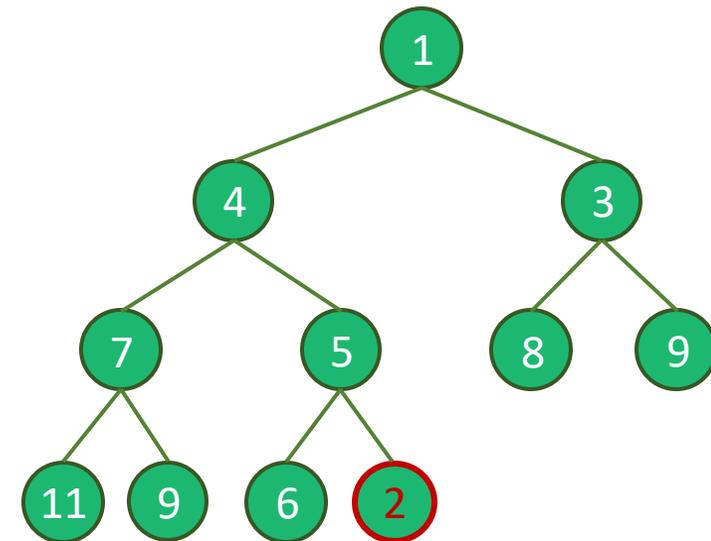
Add a node to the tree

**Problem:** where to put the node

- Requirement: (1) heap property (2) complete binary tree property
- Hint: a complete binary tree with fix number of nodes has fixed shape

**Solution:** append to the end of the complete binary tree

- How to restore Heap Property?



# Insert Element

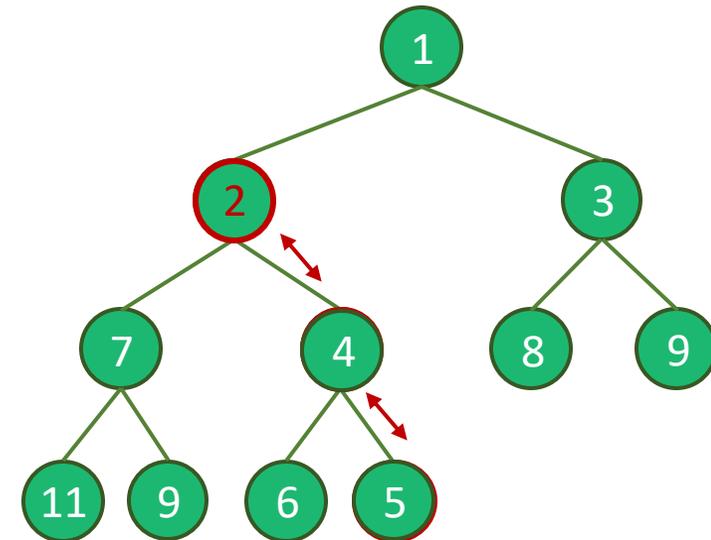
Restore heap property: Percolate Up

- Compare the modified node's priority with its parent
  - Lower: the parent's subtree is a heap, stop
  - Higher: swap with parent
- Repeat until parent has higher priority or reached root
- Complexity:  $\Theta(h) \Rightarrow \Theta(\log n)$  for being complete binary tree

Proof of correctness:

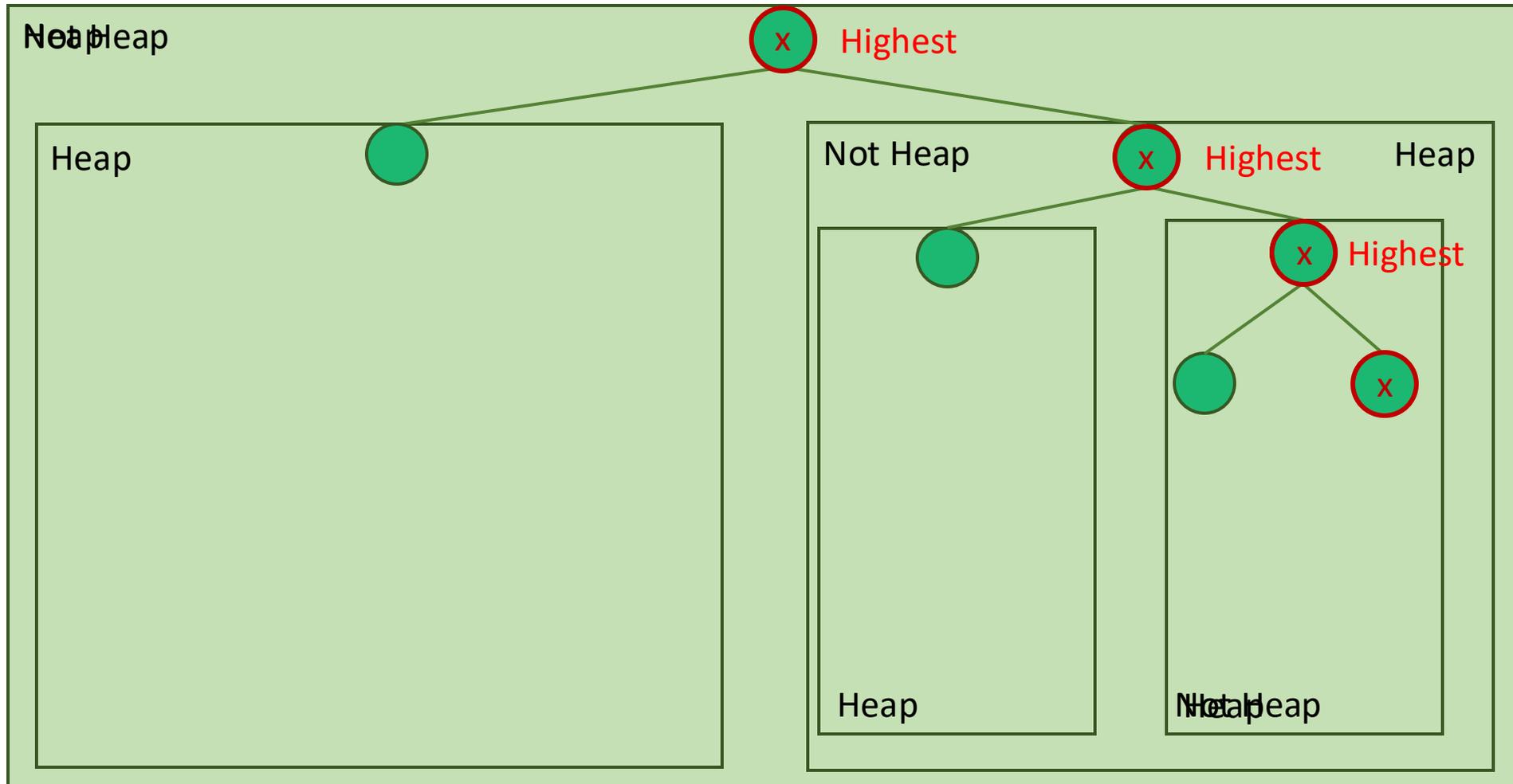
- Initially added a leaf node, a root for a heap subtree
- Swap: since the node exceeds its parent in priority and the parent dominates its subtree, after swapping, the node still roots a valid heap subtree.

Notice: If items arrive in random order, then insert is  $\mathcal{O}(1)$  on average



# Insert Element

Swapping procedure



# Summary of Operations

- Overall Requirement
  - Preserve structure property
  - Restore heap property
- insert: append at new last position, percolate-up  $\Theta(\log n)$ , on average  $\mathcal{O}(1)$
- pop: remove root, put last element at root, percolate-down  $\Theta(\log n)$

# Heap Sort

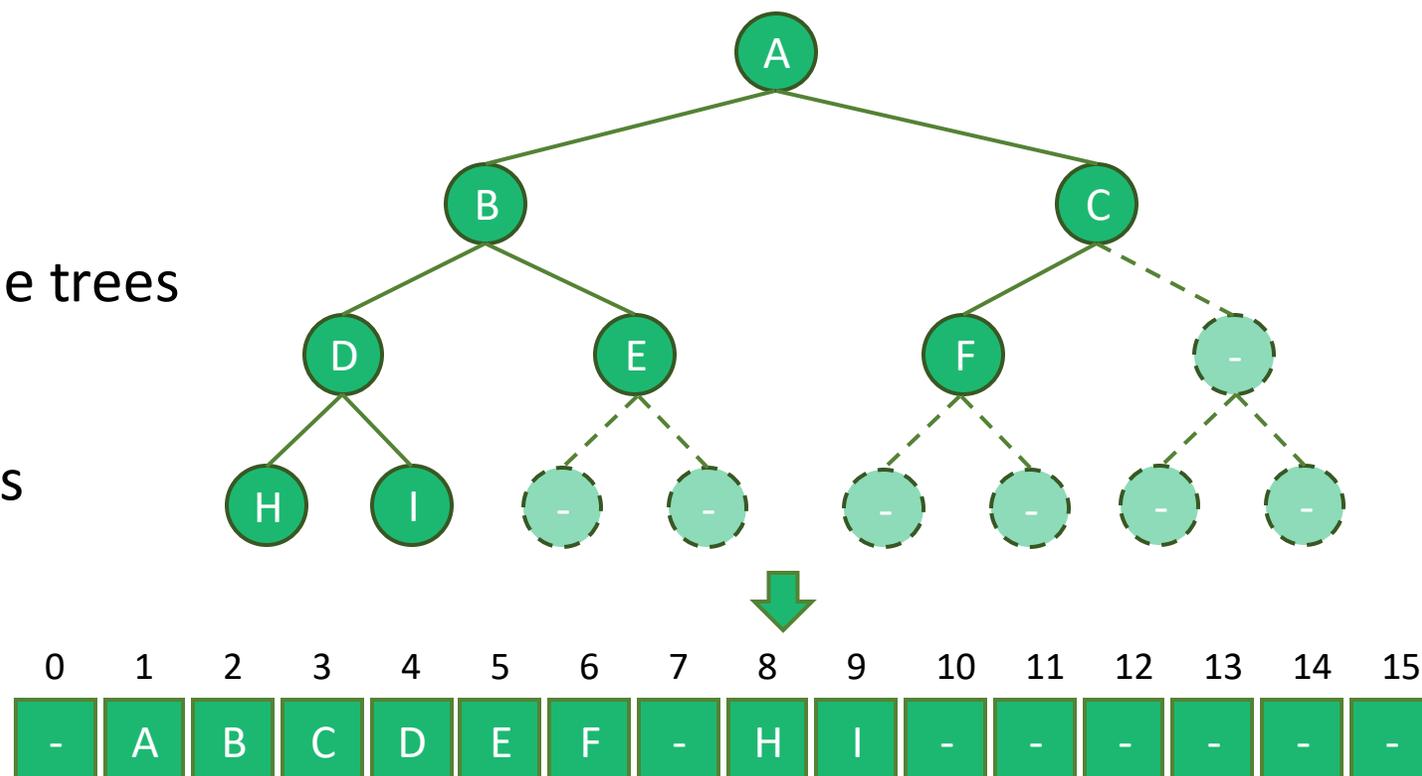
# Heap Sort

Use heap to sort elements in an array

- Add elements in the array into a min-heap
  - $O(1)$  for each element on average if add randomly
  - Add  $n$  elements:  $O(n)$
- Pop the root and restore the min-heap one by one
  - $O(\log n)$  for popping each element
  - Pop  $n$  elements:  $O(n \log n)$
- Auxiliary space complexity:  $\Theta(n)$
- *Question: can we achieve inplace sorting with this idea?*

# Array-based Binary Tree Representation

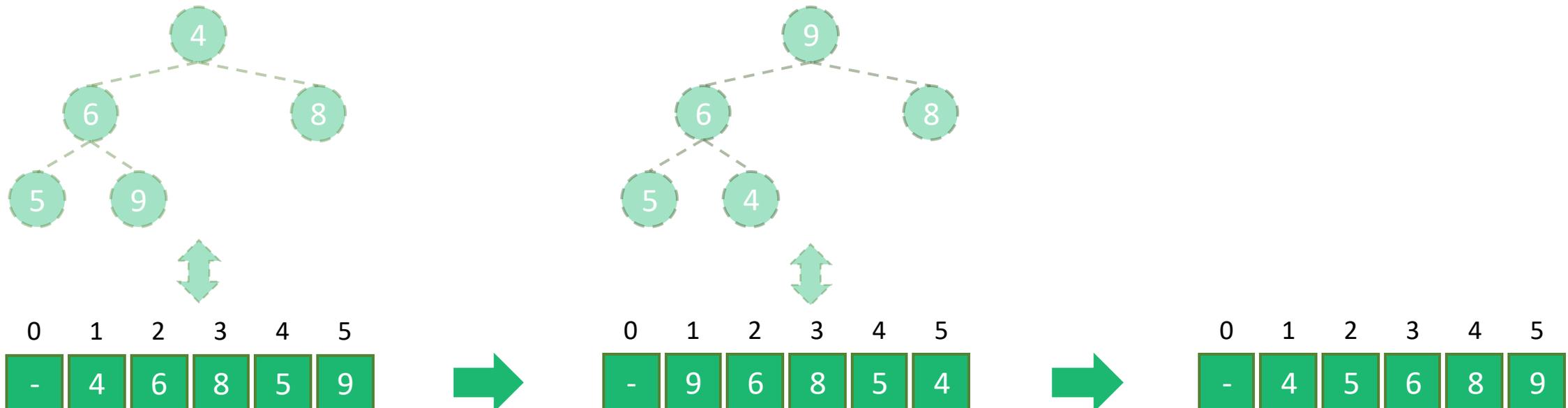
- Place root node in index 1 (wasting index 0 brings convenience for index arithmetic)
- For node with index  $i$ :
  - Left child:  $i * 2$
  - Right child:  $i * 2 + 1$
  - Parent:  $\lfloor i/2 \rfloor$
- Problem: waste of memory for sparse trees
  - e.g., chain
- Complete binary tree: no empty slots



# Heap Sort

Core idea for inplace heap sort:

- Regard the input array a complete binary tree
- Adjust the array to make a **max-heap**
- Pop the highest and add it from the tail of the array



# Heap Sort

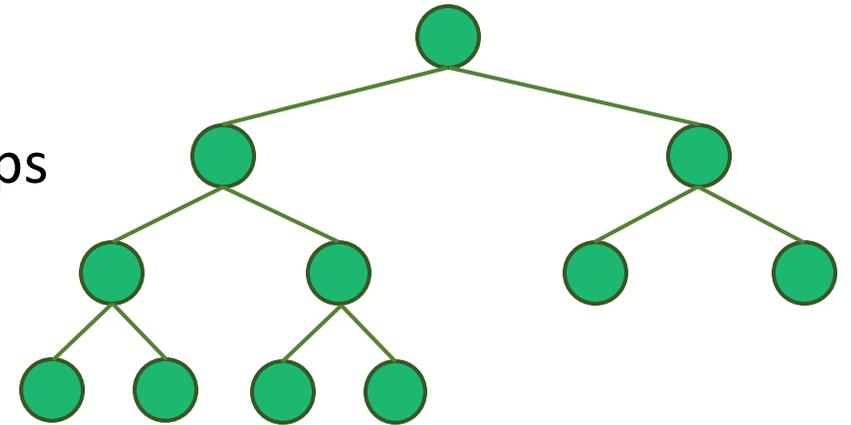
## Adjust the array into a heap

Key idea: Given a tree where the left and right subtrees are heaps, we can adjust it to a heap with PERCOLATE\_DOWN procedure

⇒ we can adjust subtrees in the second last layers into heaps

⇒ we can adjust subtrees in the third last layers into heaps

⇒ ... ⇒ we can adjust the tree into a heap



Solution: start from the **last non-leaf node**, PERCOLATE\_DOWN on the corresponding subtrees

In reverse order, we adjust the nodes in depth-decreasing order

```
BUILD_HEAP(array)
1. for i from array.length / 2 to 1:
2.   PERCOLATE_DOWN(array, array.length, i)
```

The last non-leaf node is the parent of the last leaf node

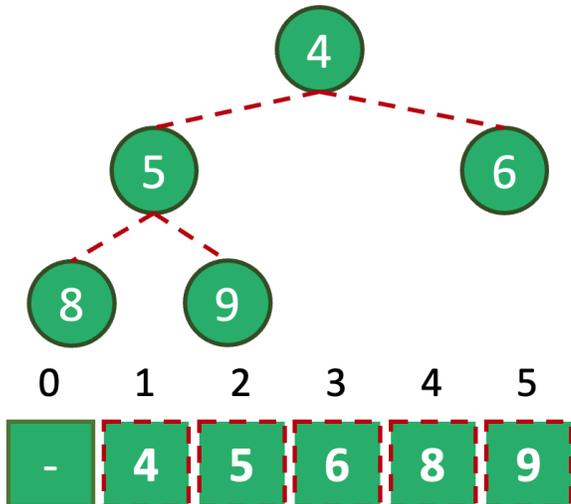
Time complexity:  $O(n \log n)$

# Heap Sort

Pop the highest and add it from the tail of the array

Key idea: after popping, the size of heap decrease by 1, the emptied slot can store the popped largest value

- Recall pop: replace root with the last element, then PERCOLATE\_DOWN
- Extension for inplace sorting: **swap** the root with the last element, then PERCOLATE\_DOWN

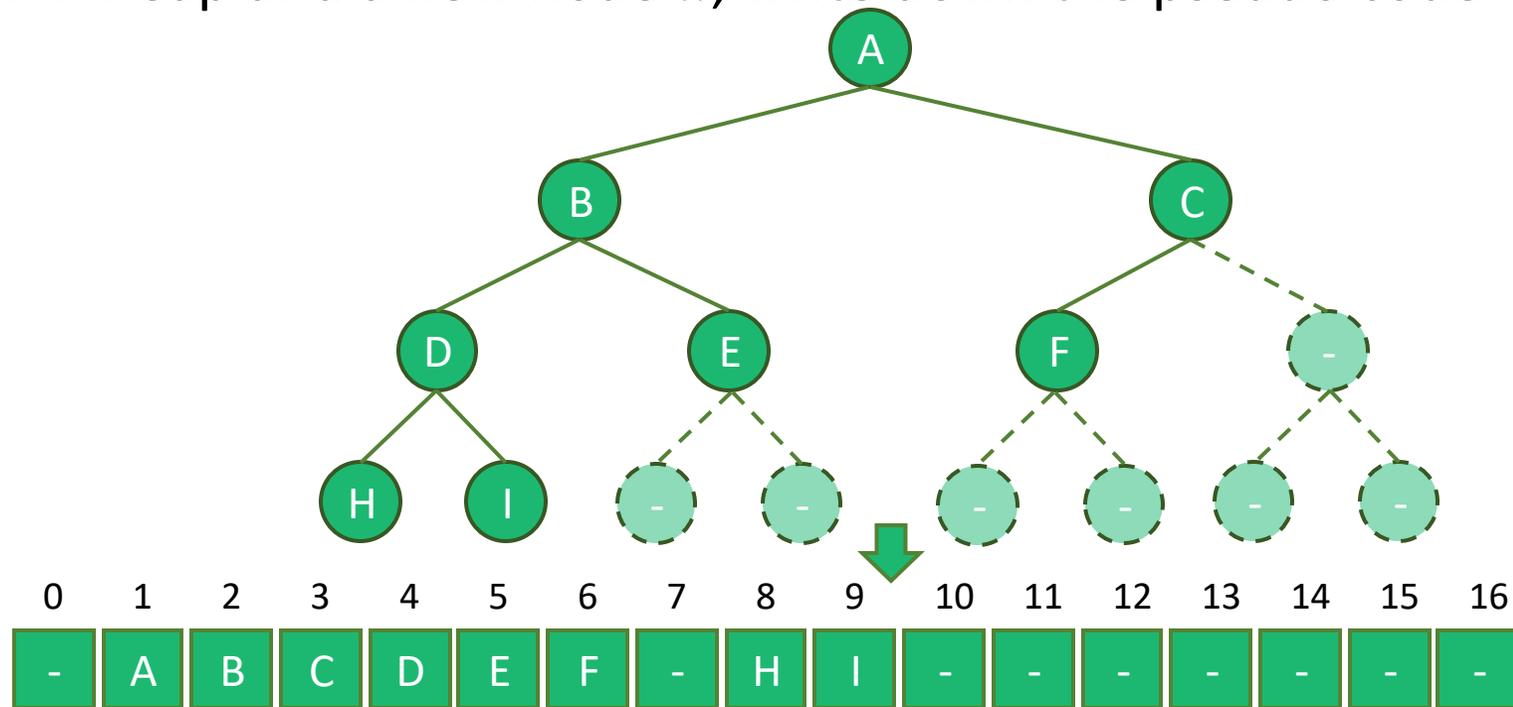


```
HEAPSORT(array)
1. BUILD_HEAP(array)
2. for i from array.length to 2:
3.     SWAP(array[1], array[i])
4.     PERCOLATE_DOWN(array, i, 1)
```

# Heap Sort

Practice (with array-based representation):

- Given an array representing the min heap, write the pseudo code for popping the minimum and do percolate down for a heap
- Given an array representing the min heap and a new node  $u$ , write down the pseudo code for insert it into the heap



# Pop Minimum

```
PERCOLATE_DOWN(heap, size, index)
1. left_child_index = 2 * index
2. right_child_index = 2 * index + 1
3. smallest = index
4. if left_child_index < size\
5.     and heap[left_child_index] < heap[smallest]:
6.     smallest = left_child_index
7. if right_child_index < size \
8.     and heap[right_child_index] < heap[smallest]:
9.     smallest = right_child_index
10. if smallest != index:
11.     SWAP(heap[index], heap[smallest])
12.     PERCOLATE_DOWN(heap, smallest)
```

```
DELETE_MIN(heap)
1. min_element = heap[1]
2. last_element = heap[heap.length]
3. heap[1] = last_element
4. heap.length -= 1
5. PERCOLATE_DOWN(heap, 1)
6. return min_element
```

# Insert Element

```
PERCOLATE_UP(heap, index)
```

```
1. parent_index = index / 2
```

```
2. # Compare the element with its parent
```

```
3. while index > 1 and heap[index] < heap[parent_index]:
```

```
4.     SWAP(heap[index], heap[parent_index])
```

```
5.     index = parent_index
```

```
6.     parent_index = index / 2
```

```
INSERT(heap, element)
```

```
1. heap[heap.length+1] = element
```

```
2. heap.length += 1
```

```
3. PERCOLATE_UP(heap, heap.length)
```

# Disjoint set

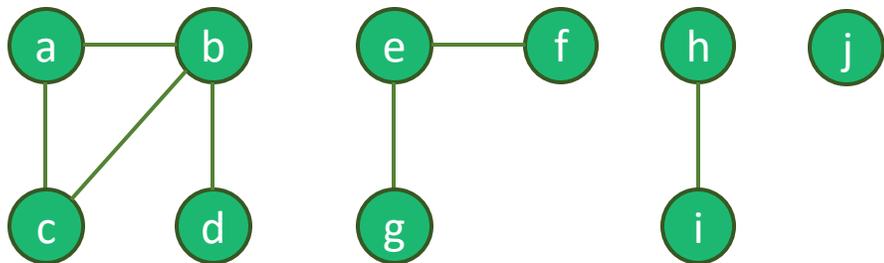
# Requirement

Consider a situation: given some persons, how to quickly support the following operations?

- Find whether individual  $x$  and  $y$  are linked through direct/indirect friend relations
- Add a new friendship relation between  $x$  and  $y$

Naïve solution: record the links, then search for all the reachable nodes from  $x$  (graph searching)

- High time and space complexity



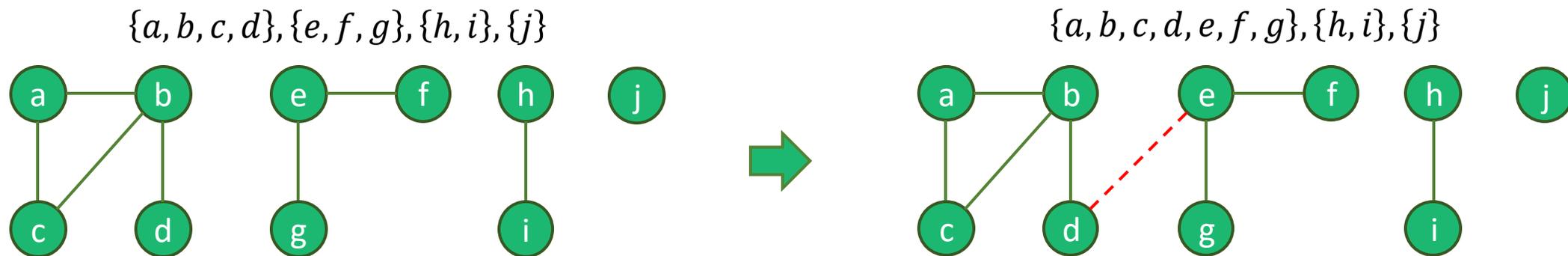
# Requirement

Consider a situation: given some persons, how to quickly support the following operations?

- Find whether individual  $x$  and  $y$  are linked through direct/indirect friend relations
- Add a new friendship relation between  $x$  and  $y$

## A set-based view

- Nodes in each linked components can reach each other
- Only care about the linked components – ignore links and record with set
- Add a link is to union two sets



## Disjoint Set

Store a collection of non-overlapping sets, also called union–find data structure or merge–find set, support operations:

- **Distinguish:** whether two elements are in the same set

$$\langle \{a, b, c, d\}, \{e, f, g\}, \{h, i\}, \{j\}, \langle a, c \rangle \rangle \Rightarrow \text{same}$$

- **Union:** given two elements, merge their set

$$\{a, b, c, d\}, \{e, f, g\}, \{h, i\}, \{j\} \Rightarrow \{a, b, c, d\}, \{e, f, g, h, i\}, \{j\}$$

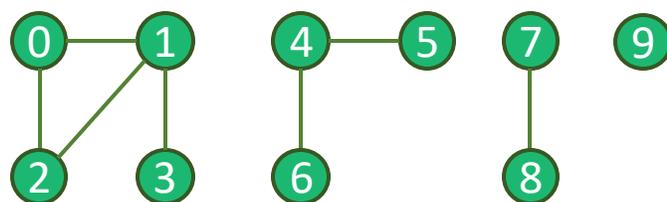
How to realize a disjoint set?

Straightforward solution: create separate collection for each set

- Distinguish: traverse all the collections and elements
- Union: find the corresponding collection, copy elements in one to the other
- **Problem:** large space and time complexity for massive number of sets and operations

## Another Naïve Solution

**Core idea:** represent each set with a member (representative), record each element's set's representative with an array



0, 1, 2, 3 belongs to 0's set  
4, 5, 6 belongs to 5's set,  
...



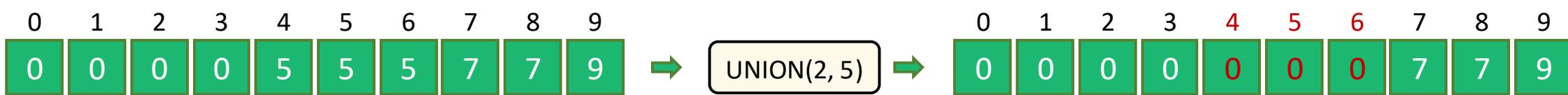
**Distinguish:** whether two elements are in the same set

- Find and compare the representative:  $\Theta(1)$



**Union:** given two elements, merge their set

- Traverse the array and modify the corresponding elements:  $\Theta(n)$



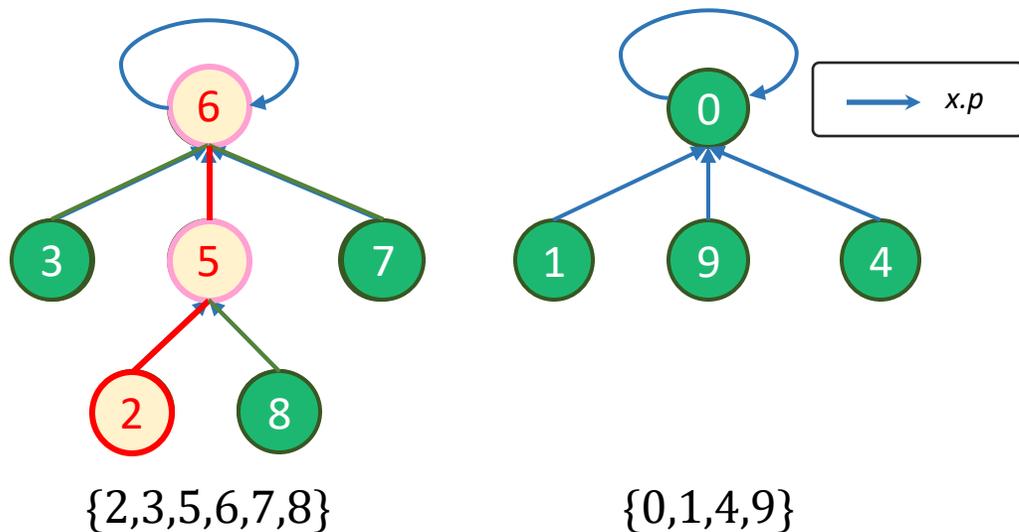
## Disjoint Set with Tree

Represent each set with a tree, where each element is a node

- Use root node as the representative

**Distinguish** whether two elements are in the same set

- Find the root through parent pointer (set the parent of the root to itself to ease coding)



```
FIND(x)
1. if x.p != x:
2.     return FIND(x.p)
3. else:
4.     return x
```

Time complexity:  $O(h)$

# Disjoint Set with Tree

Represent each set with a tree, where each element is a node

- Use root node as the representative

**Union:** given two elements ( $x$  and  $y$ ), merge their set

- Find the roots of  $x$  and  $y$ 's corresponding tree  $O(h)$
- Make  $x$ 's roots as the parent of  $y$ 's root  $O(1)$

```
UNION(x, y)
```

```
1. root_x = FIND(x)
```

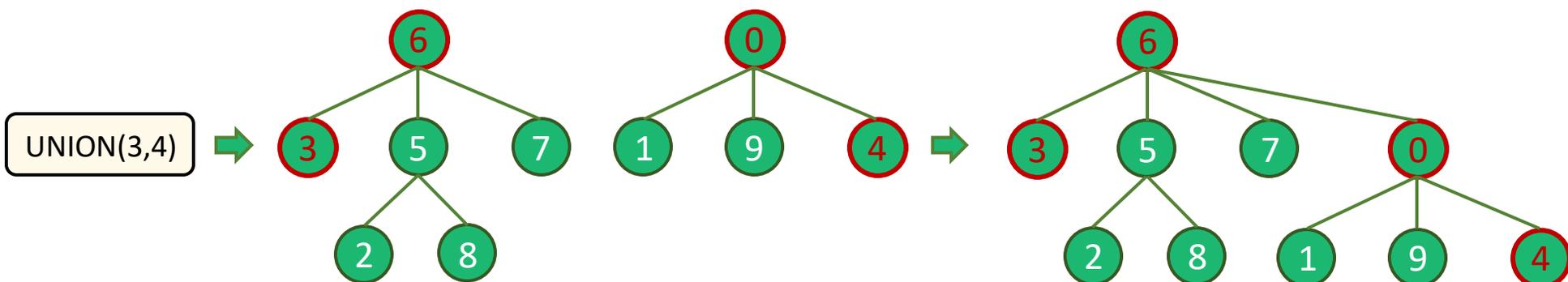
```
2. root_y = FIND(y)
```

```
3. if root_x == root_y:
```

```
4.     return
```

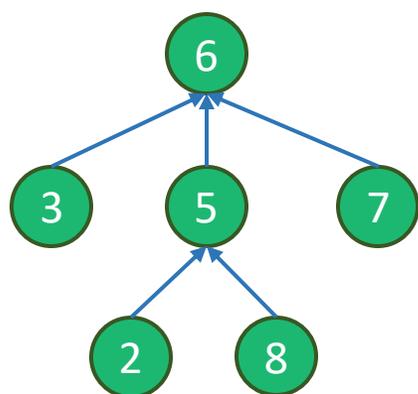
```
5. else:
```

```
6.     root_y.p = root_x
```

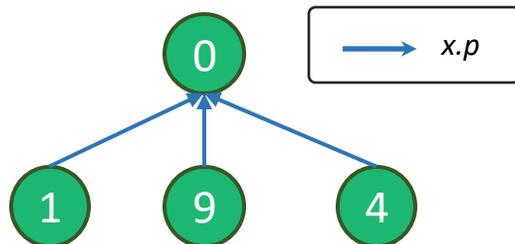


# Disjoint Set with Tree

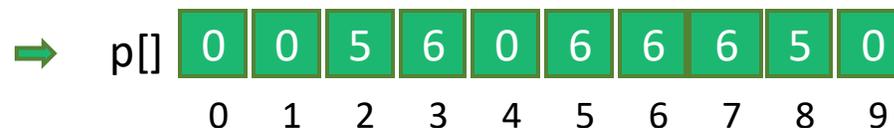
Store tree structure in an array: since only parent information is needed



{2,3,5,6,7,8}



{0,1,4,9}



```
FIND(x)
1. if p[x] != x:
2.     return FIND(p[x])
3. else:
4.     return x
```

```
UNION(x, y)
1. root_x = FIND(x)
2. root_y = FIND(y)
3. if root_x == root_y:
4.     return
5. else:
6.     p[root_y] = root_x
```

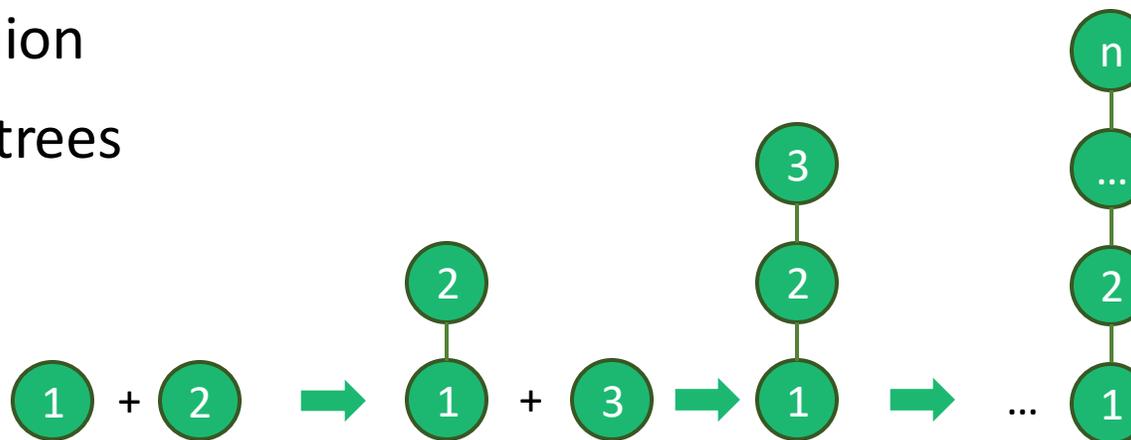
# Disjoint Set with Tree

Any potential deficiency?

- Link  $\langle 1, 2 \rangle, \langle 2, 3 \rangle, \langle 3, 4 \rangle, \langle 4, 5 \rangle, \langle 5, 6 \rangle, \dots \langle n - 1, n \rangle$
- $T(n) = \Theta(n)$  for find and union

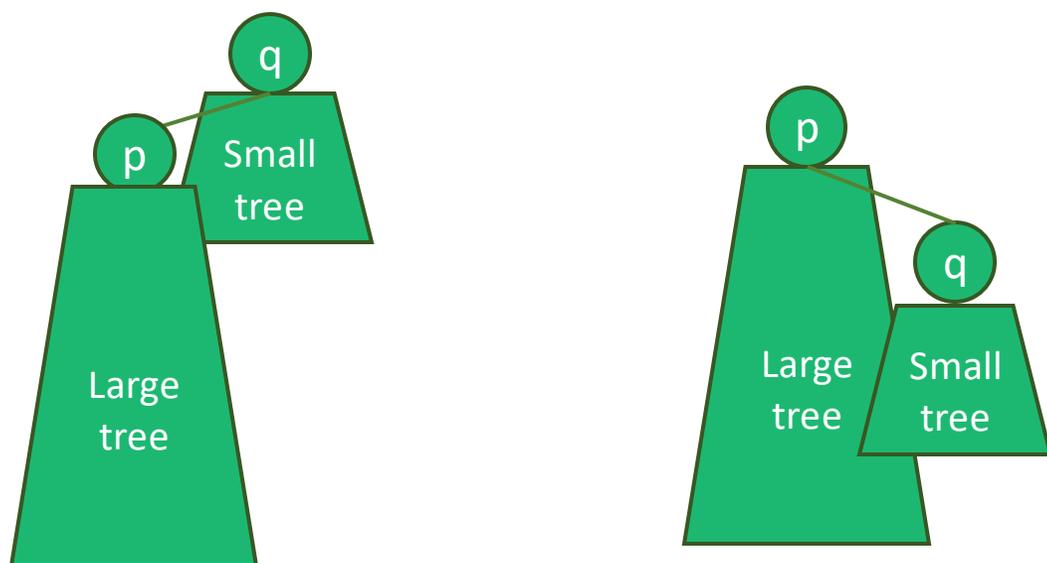
Improve complexity: avoid tall trees

- Union-by-Rank
- Path Compression



# Union by Rank

Keep track each tree's **size (number of nodes)**, link roots of smaller tree to root of larger tree.



Intuitively reduce height

```
Weight_UNION(x, y)
```

```
1. root_x = FIND(x)
```

```
2. root_y = FIND(y)
```

```
3. if root_x == root_y:
```

```
4.     return
```

```
5. else:
```

```
6.     if root_x.size < root_y.size:
```

```
7.         root_x.p = root_y
```

```
8.         root_y.size += root_x.size
```

```
9.     else:
```

```
10.        root_y.p = root_x
```

```
11.        root_x.size += root_y.size
```

## Union by Rank

**Proposition:** With union by rank, depth of any node  $x$  is at most  $\log n$ .

**Proof:**

- Notation:  $d(x)$  - depth of  $x$ ,  $|T|$  - size of a tree  $T$
- $d(x)$  possibly increase when the tree ( $T$ ) containing  $x$  is merged with another tree  $T'$ :
  - $d(x)$  increases by 1 only when  $|T'| \geq |T|$
  - The new tree's size  $|T''| = |T| + |T'| \geq 2|T|$ , at least doubles.
  - If  $d(x) = h$ , then  $2^h \leq |T|$ . Since  $|T| \leq n$ ,  $h \leq \log n$

**Conclusion:** with union by rank, time complexity for find and union operation are  $O(\log n)$

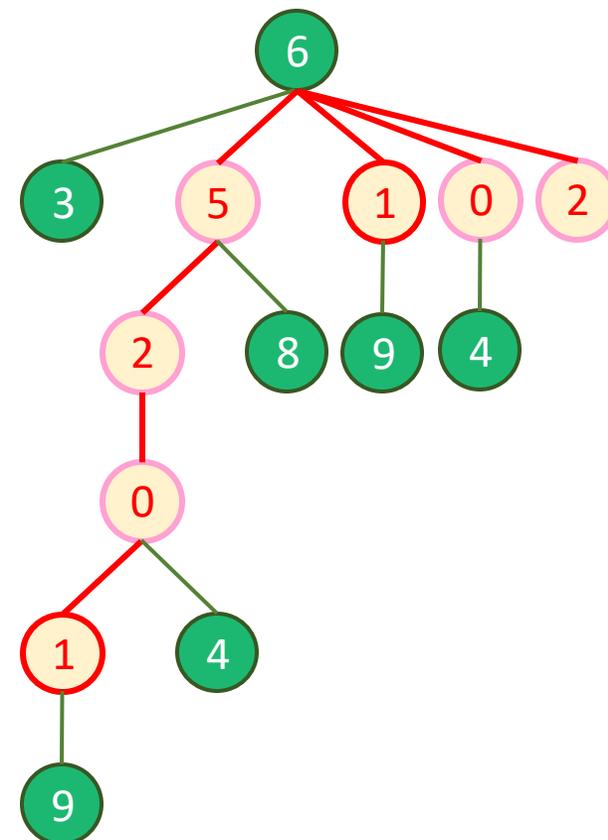
# Path Compression

After finding the root for each node, move the node to be its child

- Find:  $O(1)$  after many find operations
- Union: with  $m$  arbitrary linking operations, time complexity is roughly  $O((m + n)\log n)$ [1]

Path compression + union by rank: nearly  $O(1)$  on average

```
FIND_PC(x)
1. if x.p != x:
2.     x.p = FIND_PC(x.p)
3. return x.p
```



[1] R. Seidel and M. Sharir. Top-Down Analysis of Path Compression. Siam J. Computing, 2005, Vol. 34, No. 3, pp. 515-525.

# Summary

- Trees
- Binary Tree
- Heap
- Heap Sort
- Disjoint Set

# Thank you!

AIAA 5037 Advanced Algorithms and Data Structures